
Hopfield Neural Networks and Their Applications

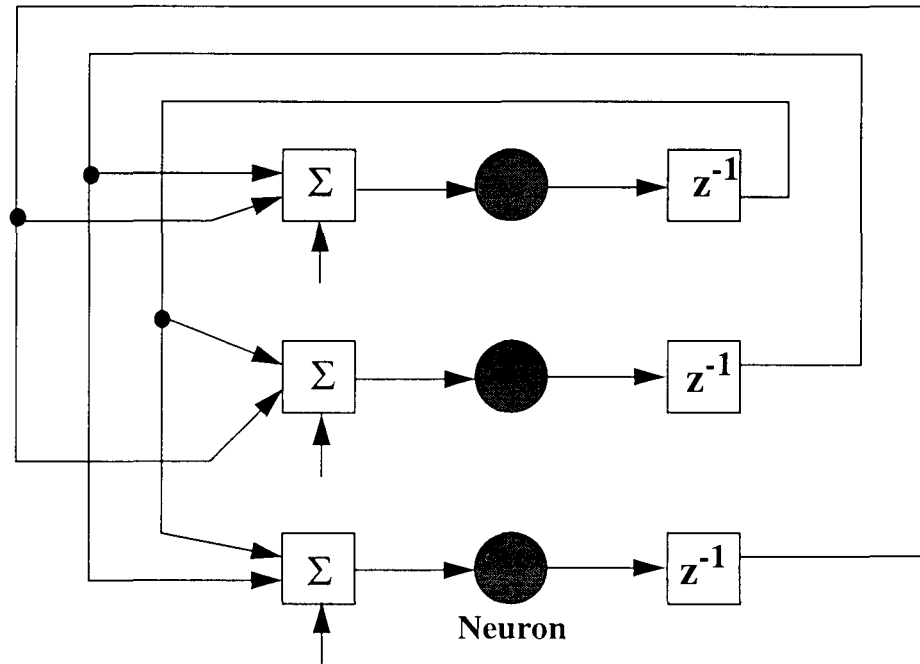
Dr. Yogananda Isukapalli

CONTENTS

- ❑ Introduction
- ❑ Hopfield Neural Networks
- ❑ Applications

The Hopfield Neural Network (HNN)

- ❑ Recurrent Neural Network
- ❑ One layer neural network with full connection

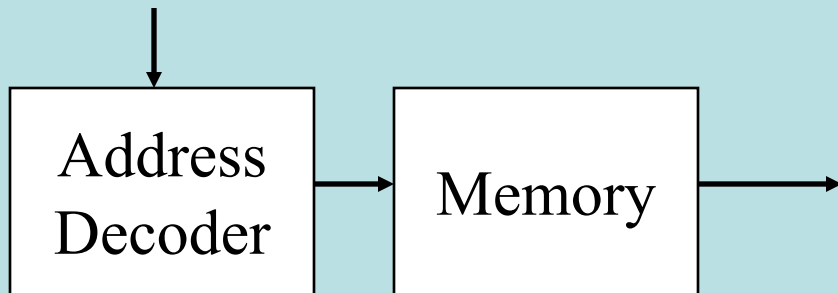


The Hopfield Neural Network

- ❑ Two aspects of Hopfield neural networks (HNN)
 - Associative memory (content addressable memory)
 - Optimization of energy function with quadratic form
- ❑ Associative memory ?

Address Addressable Memory

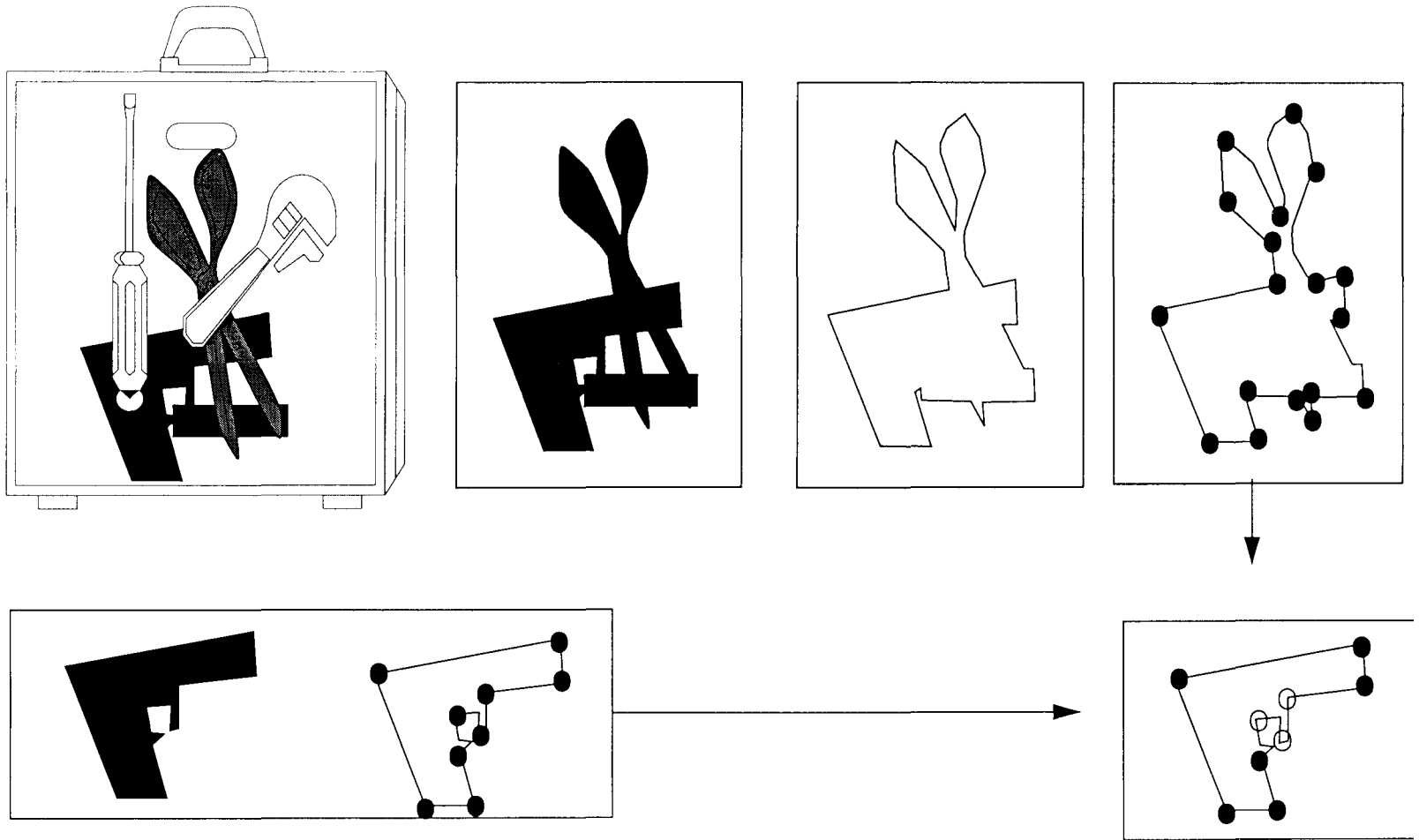
x (address vector)



Content Addressable Memory



Human perception with associate memory



Optimization

Find a minimum energy function



Applications

- ❑ DSP
- ❑ Communications
- ❑ Combinatorial optimization etc.,

Associative Memory (CAM)

- Types of CAM
 - Matrix associative memory
 - Walsh associative memory
 - Network associative memory (Hopfield Neural Network)

Linear Associative Memory

- ❑ Memory Construction for associated pattern (x_k, y_k) :

$$M_k = x_k * y_k^T$$

- ❑ Retrieval:

$$M_k * x_k = \langle x_k^T * x_k \rangle * y_k$$

- ❑ Overlay of patterns:

$$M = \sum_{k=1}^P M_k = \sum_{k=1}^P x_k \cdot y_k^T$$

- ❑ Pattern Retrieval:

$$M \cdot x_i = \sum_{k=1}^P M_k \cdot x_i = M_i \cdot x_i + \sum_{k \neq i=1}^P M_k \cdot x_i$$

Walsh Associative Memory

- Walsh functions (Hadamard Matrix)

$$H_2 = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \rightarrow \begin{bmatrix} H_2 & \overline{H_2} \\ H_2 & \overline{H_2} \end{bmatrix}$$

- Memory construction

$$M = W_k \cdot x_k^T$$

- Retrieval of Walsh Index

$$W_k^T \cdot M \cdot x_k$$

- Pattern Retrieval

$$W_k^T \cdot M$$

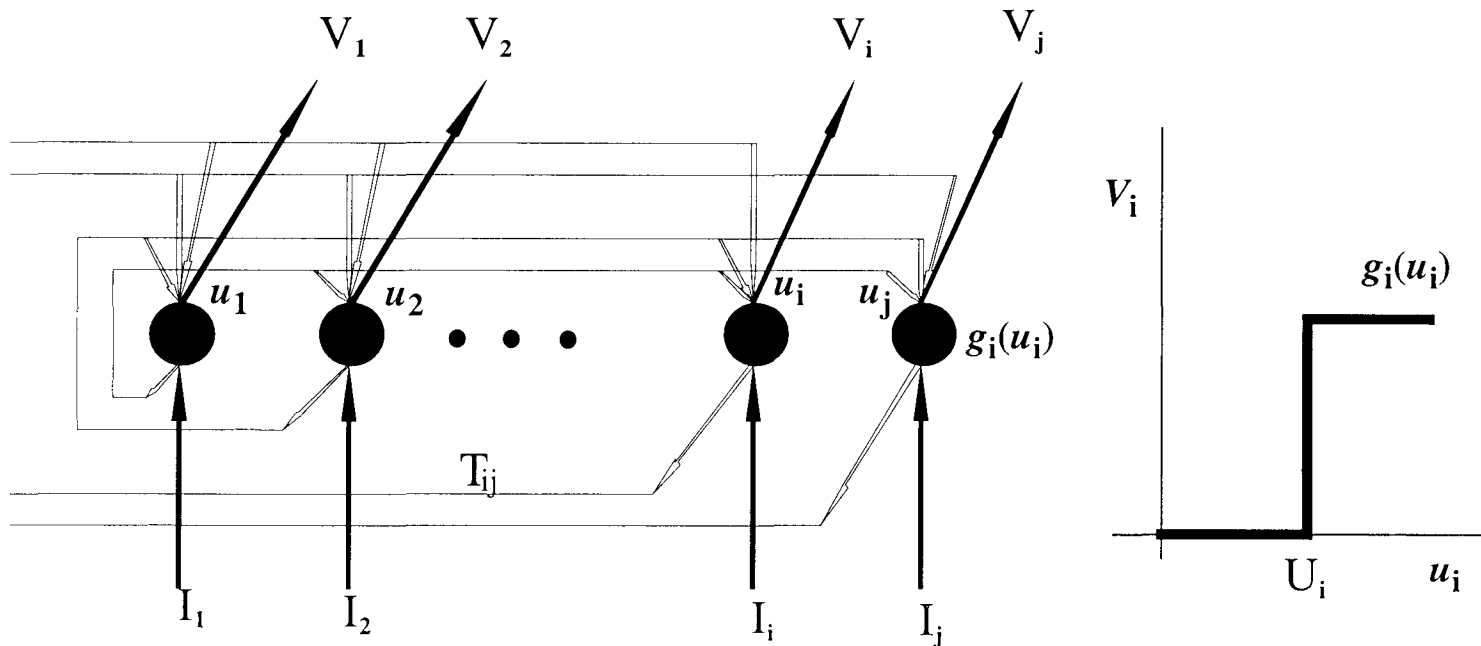
Network Associative Memory

□ Features of HNN:

- ⊕ Similar to Linear Associative Memory
- ⊕ Network Modeling
- ⊕ Asynchronous processing
- ⊕ Massive distributed and parallel processing
- ⊕ Simple architecture and analog VLSI implementation

The Hopfield Neural Network

□ The Architecture of the Hopfield Neural Network



The Hopfield Neural Network

- ❑ Constructing T (Information Storage):

$$T = \sum_{k=1}^P V^{(k)} \cdot V^{(k)T} - pI$$

- ❑ Retrieval:

- The total input to the i th neuron:

$$u_i = \sum_{i \neq j} T_{ij} V_j + I_i$$

- Updating $V_i \rightarrow V_0$ if $\sum_{j \neq i} T_{ij} V_j + I_i < U_i$

$$V_i \rightarrow V_1 \text{ if } \sum_{j \neq i} T_{ij} V_j + I_i > U_i$$

- ❑ Energy function of HNN:

$$E = -\frac{1}{2} \sum_{i \neq j} T_{ij} V_i V_j + \sum_i I_i V_i + \sum_i U_i V_i$$

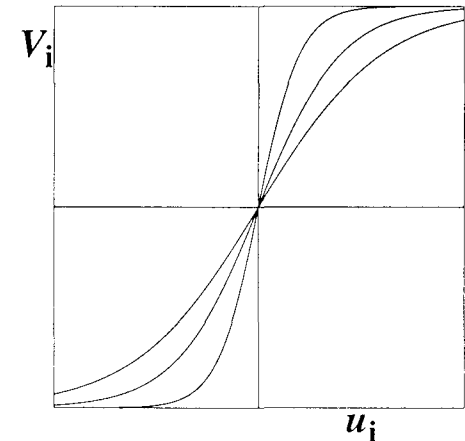
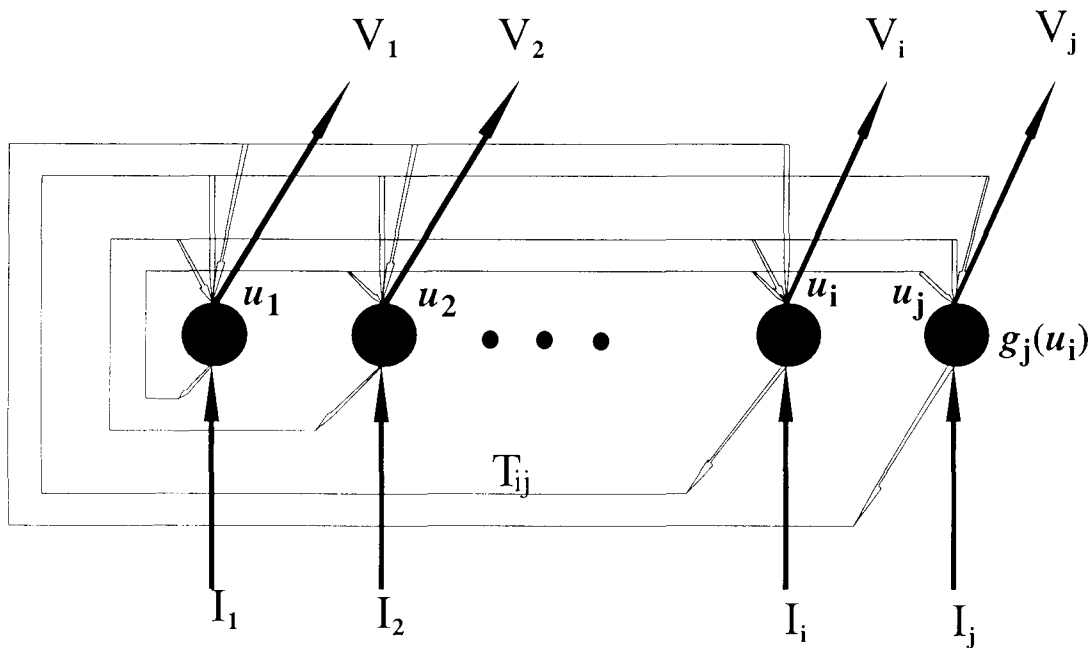
- ❑ The change ΔE in E due to changing the state of i th neuron by V_i is

$$\Delta E = -1 \cdot \left[\sum_{k=1}^P T_{ij} V_j + I_i - U_i \right] \Delta V_i$$

The Continuous Hopfield Neural Network

□ Energy function

$$E = -\frac{1}{2} \sum_{i \neq j} \sum T_{ij} V_i V_j - \sum_i I_i V_i + \sum_i \left(\frac{1}{R_i} \right) \int_0^{V_i} g_i^{-1}(v) dV$$



The Continuous Type Network

- Energy function of the Hopfield Network

$$E = -\frac{1}{2} \sum_{i \neq j} \sum T_{ij} V_i V_j - \sum_i I_i V_i + \sum_i \left(\frac{1}{R_i} \right) \int_0^{V_i} g_i^{-1}(v) dV$$

- Equation of the Motion of the Network

$$\frac{du_i}{dt} = -\frac{u_i}{R} + \sum_j T_{ij} V_j + I_i$$

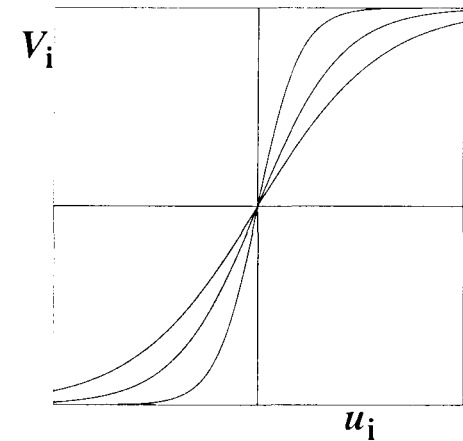
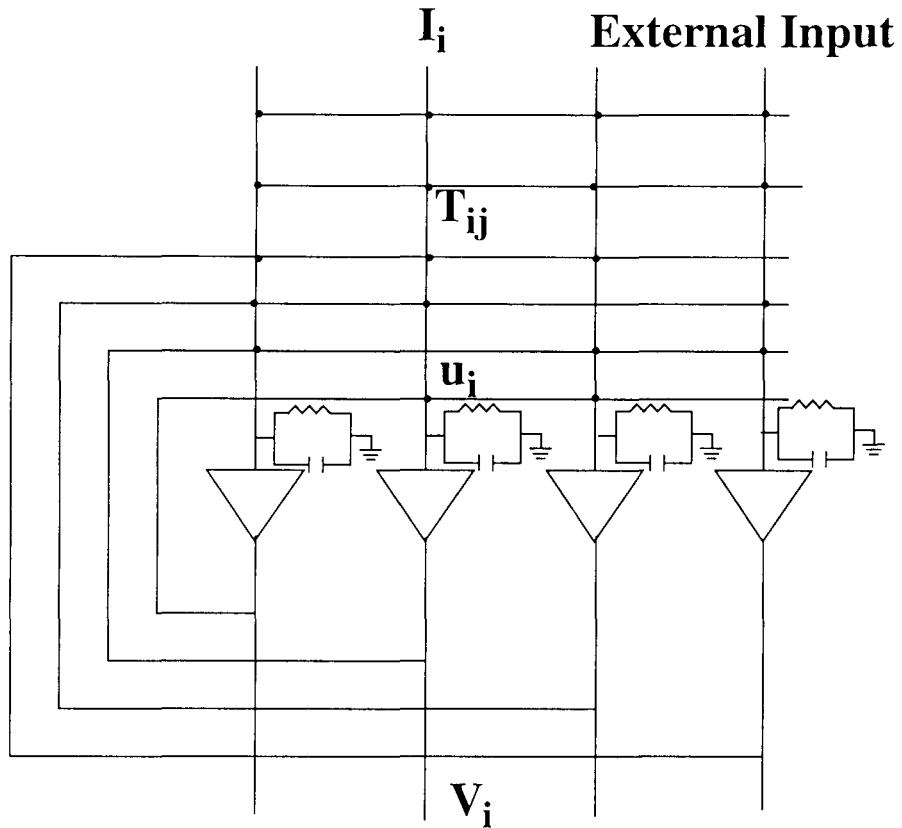
- Input-output relationship

$$g(u_i) = -\frac{1}{1 + \exp(-u_i / R)}$$

- Stability of the system

$$\frac{\partial E}{\partial t} = -C_i \cdot g_i^{-1'}(V_i) \cdot \left(\frac{\partial V_i}{\partial t} \right)^2$$

The Continuous Type Network



Application 1 (A/D Converter)

- 4 bit A/D Converter:

$$\sum_{i=0}^3 V_i \cdot 2^i \approx x$$

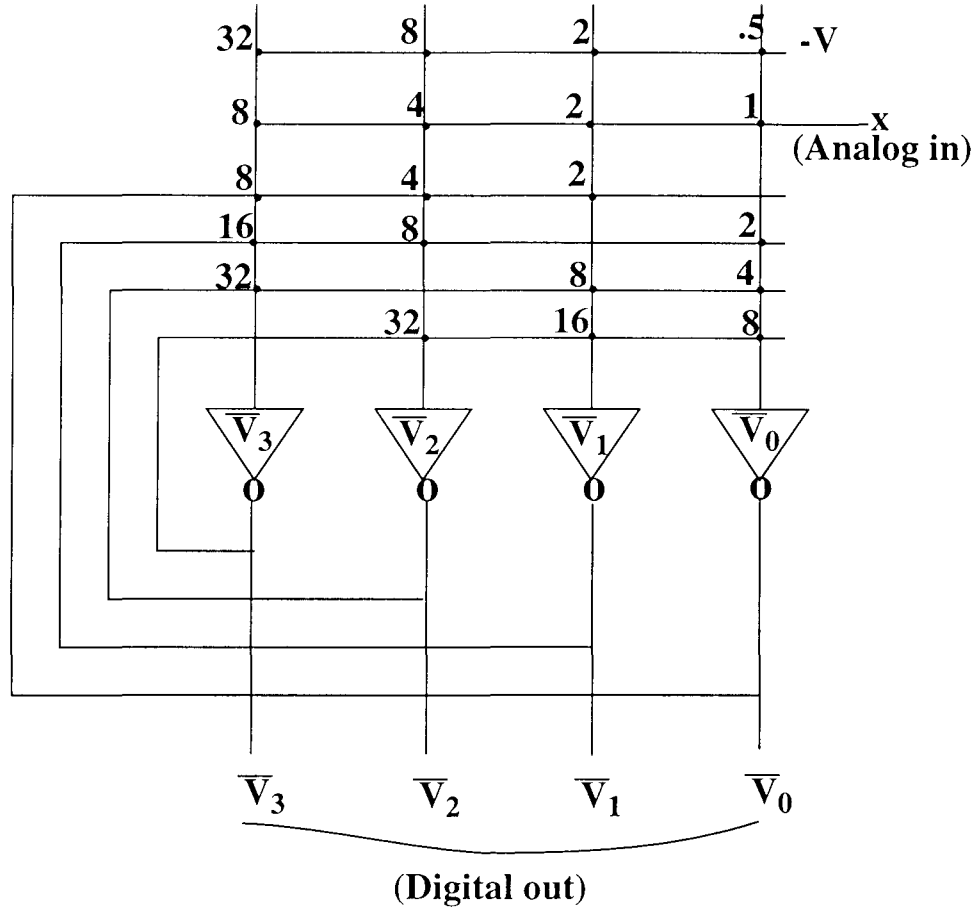
- Energy function for the A/D converter:

$$E = \left(x - \sum_{i=0}^3 V_i \cdot 2^i \right)^2 - \sum_{i=0}^3 (2^i)^2 \cdot [V_i \cdot (V_i - 1)]$$

- Energy function for Hopfield network:

$$E = -\frac{1}{2} \sum_{j=0}^3 \sum_{i \neq j=0}^3 (-2^{i+j}) V_i V_j - \sum_{i=0}^3 (-2^{(2i-1)} + 2^i x) \cdot V_i$$

Application 1 (A/D Converter)

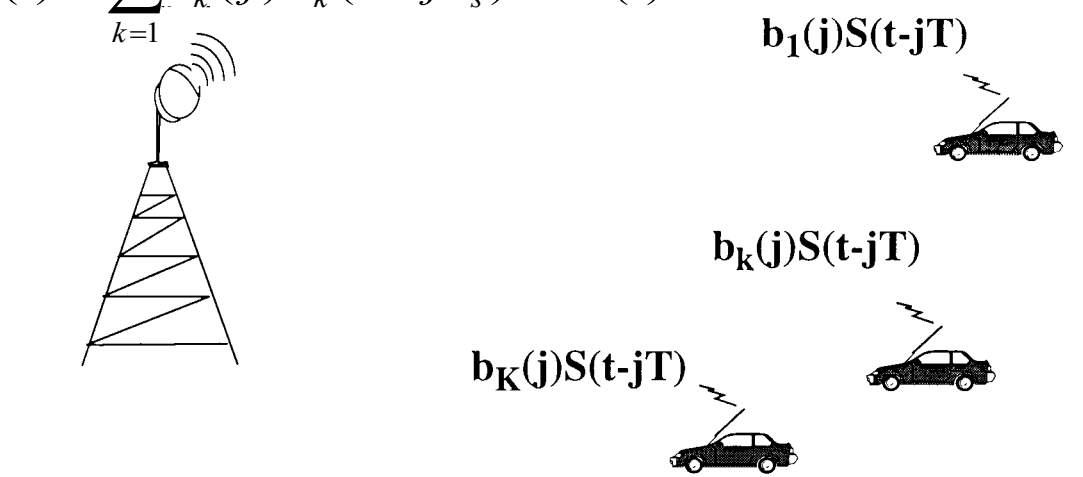


$$E = -\frac{1}{2} \sum_{j=0}^3 \sum_{i \neq j=0}^3 (-2^{i+j}) V_i V_j - \sum_{i=0}^3 (-2^{(2i-1)} + 2^i x) V_i$$

Application 2 (Multiuser Detection)

□ Problem definition:

Recover binary information sent from multiple transmitters

$$r(t) = \sum_{k=1}^K b_k(j) \cdot s_k(t - jT_s) + \sigma n(t)$$


□ The receiver observes

$$r(t) = \sum_{k=1}^K b_k(j) \cdot s_k(t - jT_s) + \sigma n(t), \quad t \in [jT_s, jT_s + T_s]$$

Application 2 (Multiuser Detection)

- Maximum likelihood detection:
 - Maximize likelihood probability:

$$P[r(t) | b] = e^{\Omega(b)}$$

$$\text{where } \Omega(b) = \int_0^T (r(t) - \sum_i b_i s_i(t))^2 dt$$

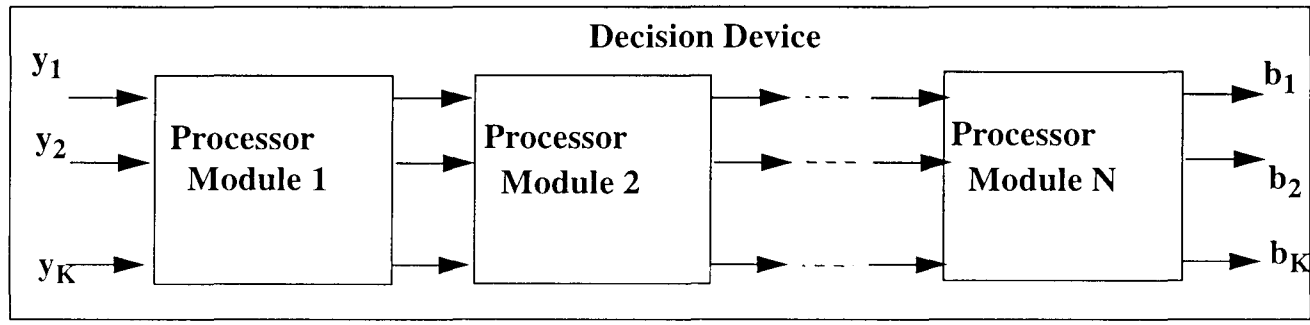
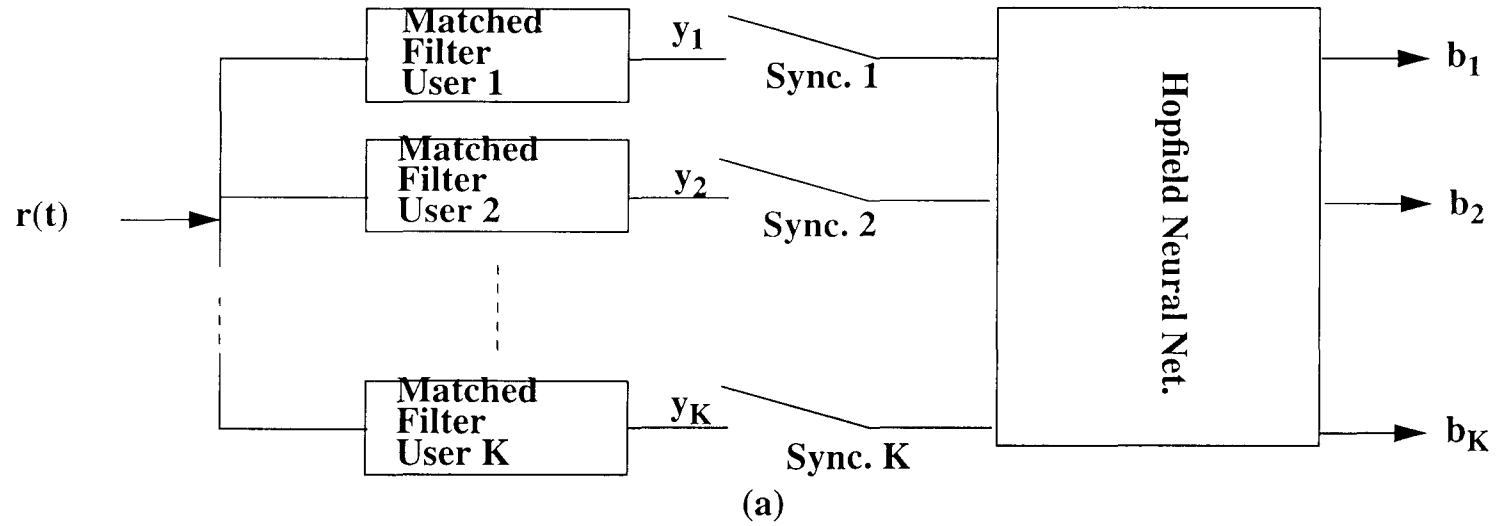
$$\hat{b} \in \arg \max_{b \in \{-1,1\}^K} \int_0^T \left[r(t) - \sum_{k=1}^K b_k s_k(t) \right]^2 dt$$

- Further developed as follows:

$$\hat{b} \in \arg \max_{b \in \{-1,1\}^K} 2y^T b - b^T H b$$

$$\text{where } y_k = \int_0^{T_s} r(t) s_k(t) dt \quad \text{and} \quad H_{ij} = \int_0^{T_s} s_i(t) s_j(t) dt$$

$$\hat{b} \in \arg \max_{b \in \{-1, 1\}^K} 2y^T b - b^T H b$$



Application 3 (Object Recognition)

- Problem definition:

Find out corresponding points between those in two objects

- An objective function for pattern recognition:

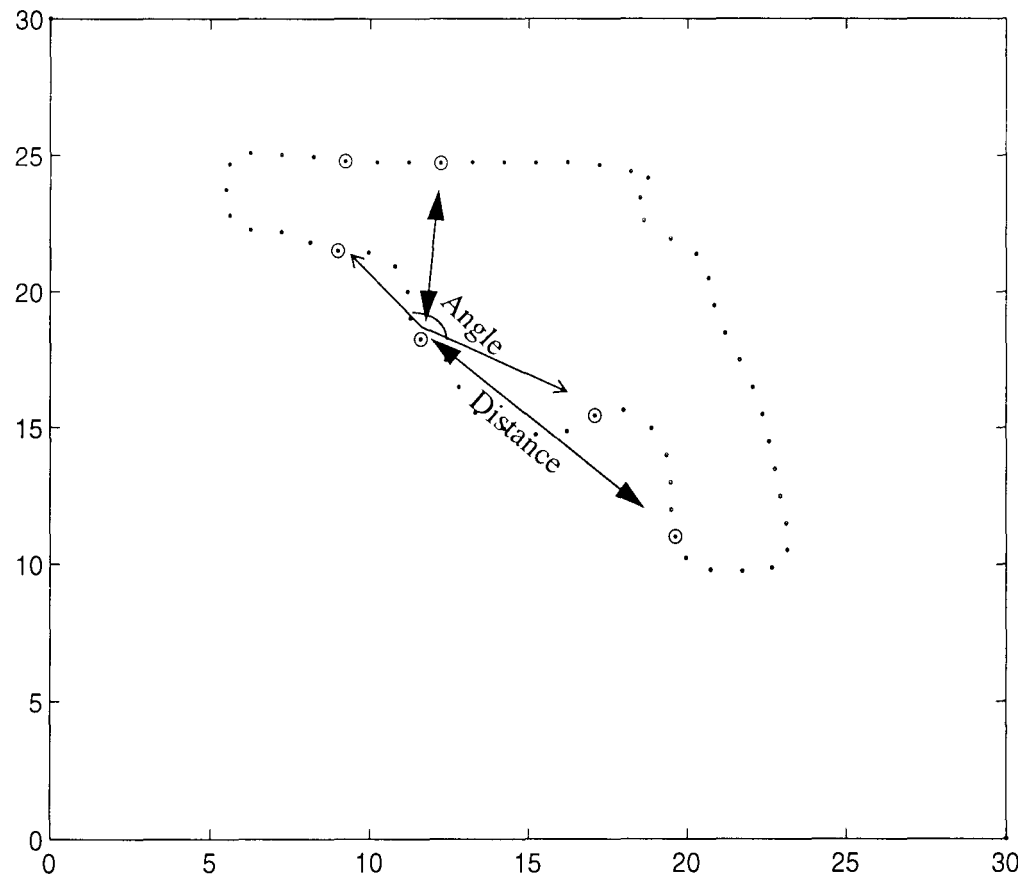
$$E = -\frac{A}{2} \sum_i \sum_j \sum_k \sum_l C_{ijkl} V_{ik} V_{jl} + \frac{q}{2} \left(\sum_i \sum_k \sum_{l \neq k} V_{ik} V_{il} + \sum_k \sum_i \sum_{j \neq i} V_{ik} V_{jk} \right)$$

- Energy function for Hopfield network:

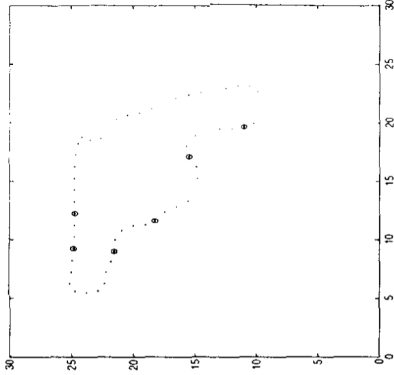
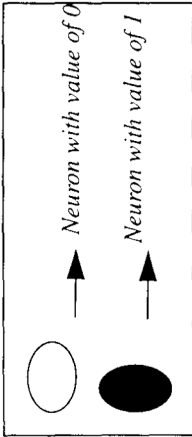
$$E = -\frac{1}{2} \sum_i \sum_j \sum_k \sum_l T_{ijkl} V_{ik} V_{jl} + \sum_i \sum_k I_{ik} V_{ik}$$

where $T_{ijkl} = AC_{ijkl} - q(\delta_{ij} + \delta_{kl}) + 2q \cdot \delta_{ij} \delta_{kl}$

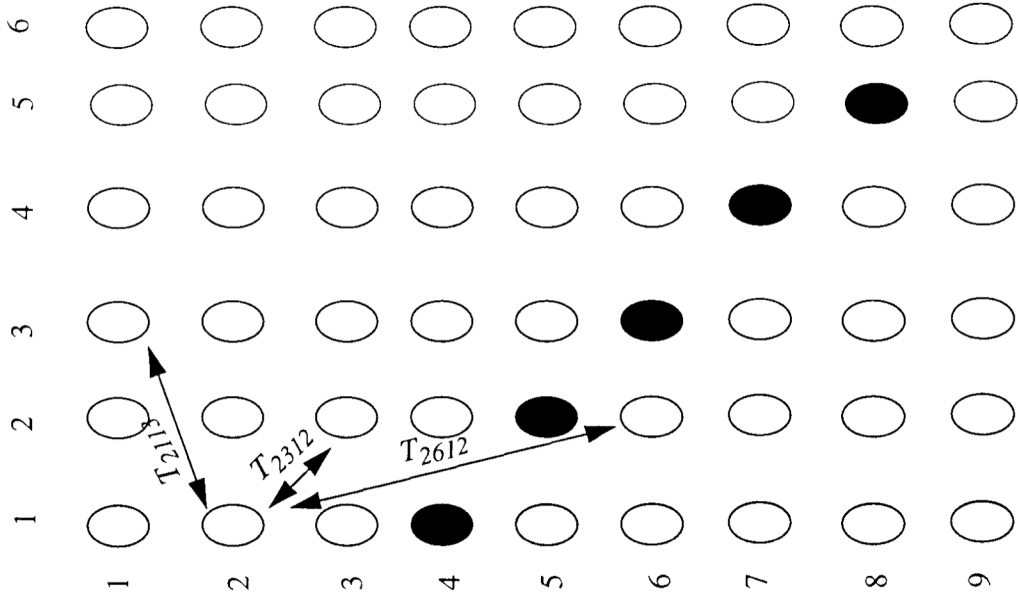
Application 3 (Object Recognition)



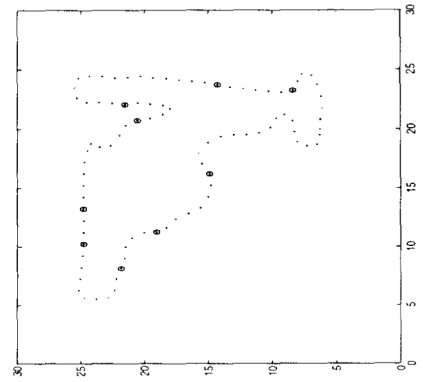
Application 3 (Object Recognition)



Model

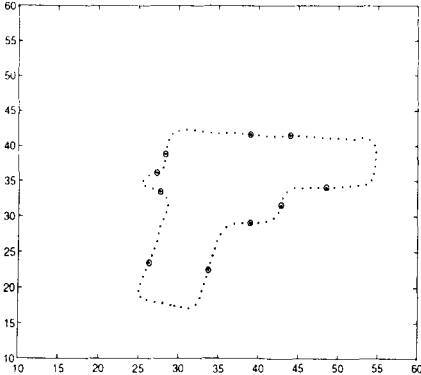


Input

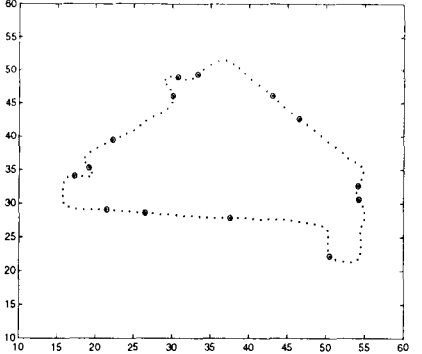


Application 3 (Object Recognition)

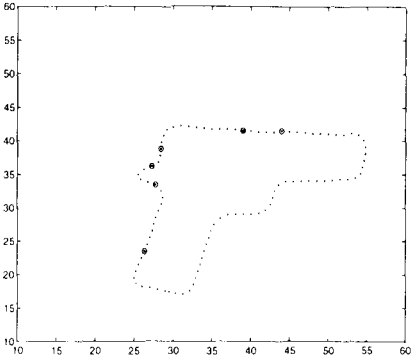
Model



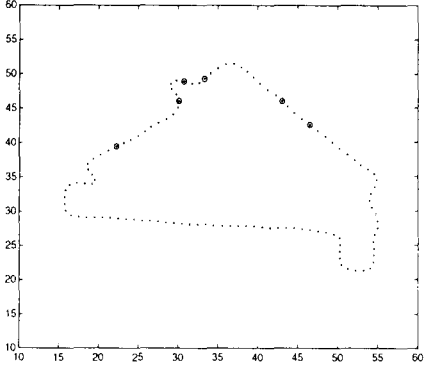
Input



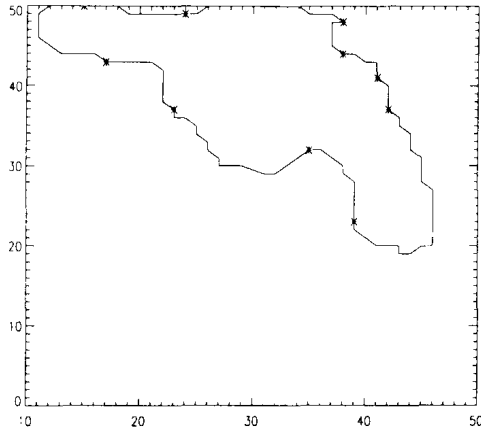
Matched Output



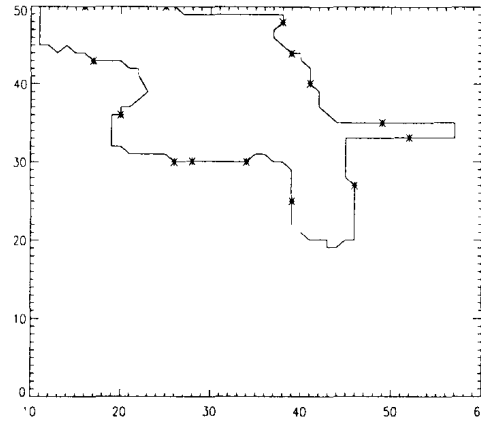
Matched Output



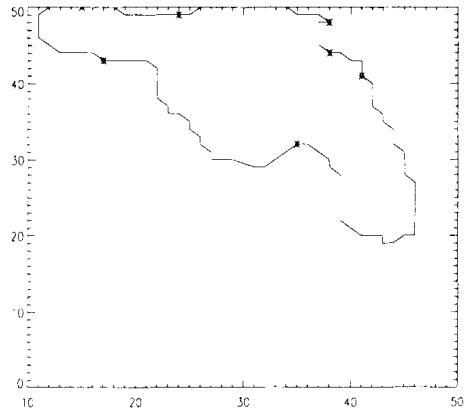
Application 3 (Object Recognition)



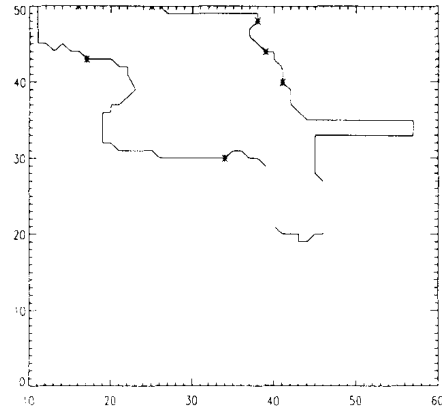
(a)



(b)



(c)



(d)